

Lecture 3: Scattering map

Arnold Diffusion and applications

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1 A priori unstable systems

2 A concrete example

We consider a 2π -periodic in time perturbation of a **pendulum** and a **rotor** described by the non-autonomous Hamiltonian,

$$\begin{aligned} H_\varepsilon(p, q, I, \varphi, t) &= H_0(p, q, I) + \varepsilon h(p, q, I, \varphi, t; \varepsilon) \\ &= P_\pm(p, q) + \frac{1}{2}I^2 + \varepsilon h(p, q, I, \varphi, t; \varepsilon) \end{aligned} \quad (1)$$

where $(p, q, I, \varphi, t) \in (\mathbb{R} \times \mathbb{T})^2 \times \mathbb{T}$ and

$$P_\pm(p, q) = \pm \left(\frac{1}{2}p^2 + V(q) \right) \quad (2)$$

and $V(q)$ is a 2π -periodic function. We will refer to $P_\pm(p, q)$ as the *pendulum*.

Note. This model just comes from a normal form around a single resonance of a nearly integrable Hamiltonian. The perturbation is arbitrary.

Theorem (Delshams-Llave-Seara06)

Consider the Hamiltonian (1) where V and h are uniformly C^{r+2} for $r \geq r_0$, sufficiently large. Assume also that

- H1** The potential $V : \mathbb{T} \rightarrow \mathbb{R}$ has a unique global maximum at $q = 0$ which is non-degenerate. Denote by $(q_0(t), p_0(t))$ an orbit of the pendulum $P_{\pm}(p, q)$ homoclinic to $(0, 0)$.
- H2** The Melnikov potential, associated to h (and to the homoclinic orbit (p_0, q_0)):

$$\mathcal{L}(I, \varphi, s) = - \int_{-\infty}^{+\infty} (h(p_0(\sigma), q_0(\sigma), I, \varphi + I\sigma, s + \sigma; 0) - h(0, 0, I, \varphi + I\sigma, s + \sigma; 0)) d\sigma \quad (3)$$

satisfies concrete non-degeneracy conditions.

- H3** The perturbation term h satisfies concrete non-degeneracy conditions.

Then, there is $\varepsilon^* > 0$ such that for $0 < \varepsilon < \varepsilon^*$, and for any interval $[I_-^*, I_+^*]$, there exists a trajectory $\tilde{x}(t)$ of the system (1) such that for some $T > 0$,

$$I(\tilde{x}(0)) \leq I_-^*; \quad I(\tilde{x}(T)) \geq I_+^*.$$

Remark Arbitrary **excursions** in the I variable can also be realized.

Hypotheses **H1**, **H2** and **H3** are \mathcal{C}^2 generic, so, the following short version of the Theorem also holds:

Theorem (Delshams-Huguet09)

Consider the Hamiltonian (1) and assume that V and h are \mathcal{C}^{r+2} functions which are \mathcal{C}^2 generic, with $r > r_0$, large enough. Then there is $\varepsilon^ > 0$ such that for $0 < |\varepsilon| < \varepsilon^*$ and for any interval $[I_-^*, I_+^*]$, there exists a trajectory $\tilde{x}(t)$ of the system with Hamiltonian (1) such that for some $T > 0$*

$$I(\tilde{x}(0)) \leq I_-^*; \quad I(\tilde{x}(T)) \geq I_+^*.$$

Remark A (non optimal) value of r_0 which follows from our argument is $r_0 = 242$.

The main idea of the proof is to use the two (or more) dynamics on $\tilde{\Lambda}$.

- Find a big invariant **saddle** object: a **NHIM** (normally hyperbolic invariant manifold: a global version of a center manifold) $\tilde{\Lambda}$ with **transverse** associated stable and unstable manifolds along some homoclinic manifold $\Gamma: \mathcal{W}^u(\tilde{\Lambda}) \pitchfork_{\Gamma} \mathcal{W}^s(\tilde{\Lambda})$.
- Compute the invariant objects (typically tori \mathcal{T}) which may prevent instability for the **inner dynamics** of the NHIM.
- Compute an **scattering map** $S = S^{\Gamma} : H_- \subset \tilde{\Lambda} \rightarrow H_+ \subset \tilde{\Lambda}$ on the NHIM associated to Γ and consider it as an **outer** dynamics on the NHIM (a second dynamics on Γ).
- Check that $S(\mathcal{T}_i) \pitchfork \mathcal{T}_{i+1}$ for a sequence of tori $\{\mathcal{T}_i\}_{i=1}^N$ with $|I_N - I_1| = \mathcal{O}(1)$, and construct a **transition chain** of whiskered tori, i.e. $\mathcal{W}^u(\mathcal{T}_i) \pitchfork \mathcal{W}^s(\mathcal{T}_{i+1})$.
- Standard shadowing methods provide an orbit that follows closely the **transition chain**.

Consider a pendulum and a rotor plus a time periodic perturbation depending on two harmonics in the variables (φ, s) :

$$H_\varepsilon(p, q, I, \varphi, s) = \pm \left(\frac{p^2}{2} + \cos q - 1 \right) + \frac{I^2}{2} + \varepsilon h(q, \varphi, s) \quad (4)$$

$$\begin{aligned} h(q, \varphi, s) &= f(q)g(\varphi, s), \\ f(q) &= \cos q, \quad g(\varphi, s) = a_1 \cos \varphi + a_2 \cos s. \end{aligned} \quad (5)$$

Theorem

Assume that $a_1 a_2 \neq 0$ in (4)-(5). Then, for any $I^ > 0$, there exists $\varepsilon^* = \varepsilon^*(I^*, a_1, a_2) > 0$ such that for any ε , $0 < \varepsilon < \varepsilon^*$, there exists a trajectory $(p(t), q(t), I(t), \varphi(t))$ such that for some $T > 0$*

$$I(0) \leq -I^* < I^* \leq I(T).$$

We have two important dynamics associated to the system: the **inner** and the **outer** dynamics.

$$\tilde{\Lambda} = \{(0, 0, I, \varphi, s); I \in [-I^*, I^*], (\varphi, s) \in \mathbb{T}^2\}.$$

is a 3D *Normally Hyperbolic Invariant Manifold* (NHIM) with associated 4D stable $W_\varepsilon^s(\tilde{\Lambda})$ and unstable $W_\varepsilon^u(\tilde{\Lambda})$ invariant manifolds.

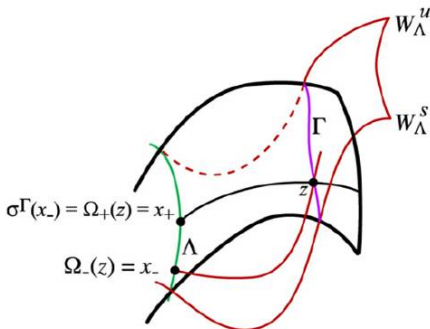
- The *inner dynamics* is the dynamics restricted to $\tilde{\Lambda}$. (**Inner map**)
- The *outer dynamics* is the dynamics restricted to its invariant manifolds. (**Scattering map**)

Remark: for simplicity, in our case $\tilde{\Lambda} = \tilde{\Lambda}_\varepsilon$.

Let $\tilde{\Lambda}$ be a NHIM with invariant manifolds intersecting transversally along a homoclinic manifold Γ . A scattering map is a map S defined by $S(\tilde{x}_-) = \tilde{x}_+$ if there exists $\tilde{z} \in \Gamma$ satisfying

$$|\phi_t^\varepsilon(\tilde{z}) - \phi_t^\varepsilon(\tilde{x}_\mp)| \rightarrow 0 \text{ as } t \rightarrow \mp\infty$$

that is, $W_\varepsilon^u(\tilde{x}_-)$ intersects transversally $W_\varepsilon^s(\tilde{x}_+)$ in \tilde{z} .



S is symplectic and exact (Delshams -de la Llave - Seara 2008) and takes the form:

$$S_\varepsilon(I, \varphi, s) = \left(I + \varepsilon \frac{\partial \mathcal{L}^*}{\partial \theta}(I, \theta) + \mathcal{O}(\varepsilon^2), \theta - \varepsilon \frac{\partial \mathcal{L}^*}{\partial I}(I, \theta) + \mathcal{O}(\varepsilon^2), s \right),$$

where $\theta = \varphi - Is$ and $\mathcal{L}^*(I, \theta)$ is the **Reduced Poincaré function**, or more simply in the variables (I, θ) :

$$S_\varepsilon(I, \theta) = \left(I + \varepsilon \frac{\partial \mathcal{L}^*}{\partial \theta}(I, \theta) + \mathcal{O}(\varepsilon^2), \theta - \varepsilon \frac{\partial \mathcal{L}^*}{\partial I}(I, \theta) + \mathcal{O}(\varepsilon^2) \right),$$

- The variable s remains fixed under S_ε : it plays the role of a parameter
- Up to **first order** in ε , S_ε is the **$-\varepsilon$ -time flow** of the Hamiltonian $\mathcal{L}^*(I, \theta)$
- The scattering map jumps $\mathcal{O}(\varepsilon)$ distances along the level curves of $\mathcal{L}^*(I, \theta)$

To get a scattering map we search for homoclinic orbits to $\tilde{\Lambda}_\varepsilon$

Proposition

Given $(I, \varphi, s) \in [-I^*, I^*] \times \mathbb{T}^2$, assume that the real function

$$\tau \in \mathbb{R} \mapsto \mathcal{L}(I, \varphi - I\tau, s - \tau) \in \mathbb{R}$$

has a non degenerate critical point $\tau^* = \tau(I, \varphi, s)$, where $\mathcal{L}(I, \varphi, s) =$

$$\int_{-\infty}^{+\infty} h(p_0(\sigma), q_0(\sigma), I, \varphi + I\sigma, s + \sigma; 0) - h(0, 0, I, \varphi + I\sigma, s + \sigma; 0) d\sigma.$$

Then, for $0 < |\varepsilon|$ small enough, there exists a transversal homoclinic point \tilde{z} to $\tilde{\Lambda}_\varepsilon$, which is ε -close to the point $\tilde{z}^*(I, \varphi, s) = (p_0(\tau^*), q_0(\tau^*), I, \varphi, s) \in W^0(\tilde{\Lambda})$:

$$\tilde{z} = \tilde{z}(I, \varphi, s) = (p_0(\tau^*) + O(\varepsilon), q_0(\tau^*) + O(\varepsilon), I, \varphi, s) \in W^u(\tilde{\Lambda}_\varepsilon) \cap W^s(\tilde{\Lambda}_\varepsilon).$$

In our model the perturbation is

$$h(p, q, I, \varphi, s) = \cos q (a_1 \cos \varphi + a_2 \cos s)$$

and the Melnikov potential becomes

$$\mathcal{L}(I, \varphi, s) = A_1(I) \cos(k_1 \varphi + l_1 s) + A_2 \cos(k_2 \varphi + l_2 s),$$

where $A_1(I) = \frac{2\pi I a_1}{\sinh(\frac{I\pi}{2})}$ and $A_2 = \frac{2\pi a_2}{\sinh(\frac{\pi}{2})}$.

Definition

The **Reduced Poincaré function** is

$$\mathcal{L}^*(I, \theta) = \mathcal{L}(I, \varphi - I\tau^*(I, \varphi, s), s - \tau^*(I, \varphi, s)),$$

where $\theta = \varphi - I s$.

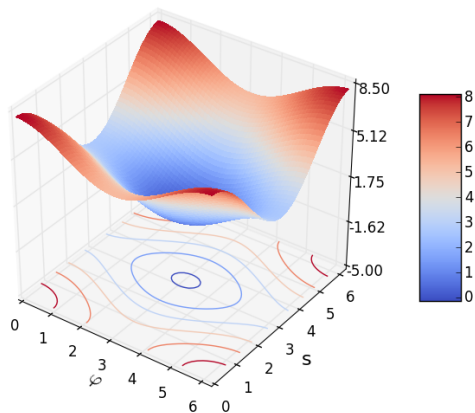


Figure: The Melnikov Potential, $\mu = a_1/a_2 = 0.6$, $I = 1$.

We look for τ^* such that $\frac{\partial \mathcal{L}}{\partial \tau}(I, \varphi - I\tau^*, s - \tau^*) = 0$.

Different view-points for $\tau^* = \tau^*(I, \varphi, s)$

- Look for critical points of \mathcal{L} on the straight line $R(I, \varphi, s) = \{(\varphi - I\tau, s - \tau), \tau \in \mathbb{R}\}$.
- Look for intersections between $R(I, \varphi, s) = \{(\varphi - I\tau, s - \tau), \tau \in \mathbb{R}\}$ and a **crest** which is a curve of equation

$$\frac{\partial \mathcal{L}}{\partial \tau}(I, \varphi - I\tau, s - \tau)|_{\tau=0} = 0.$$

Definition - Crests (Delshams-Huguet 2011)

For each I , we call *crest* $\mathcal{C}(I)$ the set of curves in the variables (φ, s) of equation

$$I \frac{\partial \mathcal{L}}{\partial \varphi}(I, \varphi, s) + \frac{\partial \mathcal{L}}{\partial s}(I, \varphi, s) = 0. \quad (6)$$

which in our case can be rewritten as

$$\mu \alpha(I) \sin \varphi + \sin s = 0, \quad \text{with } \alpha(I) = \frac{\sinh(\frac{\pi}{2}) I^2}{\sinh(\frac{\pi I}{2})}, \quad \mu = \frac{a_{10}}{a_{01}}. \quad (7)$$

- For any I , the critical points of the Melnikov potential $\mathcal{L}(I, \cdot, \cdot)$ $((0, 0)$, $(0, \pi)$, $(\pi, 0)$ and (π, π) : one maximum, one minimum point and two saddle points) always belong to the crest $\mathcal{C}(I)$.
- $\mathcal{L}^*(I, \theta)$ is nothing else but \mathcal{L} evaluated on the crest $\mathcal{C}(I)$.
- $\theta = \varphi - Is$ is constant on the straight line $R(I, \varphi, s)$

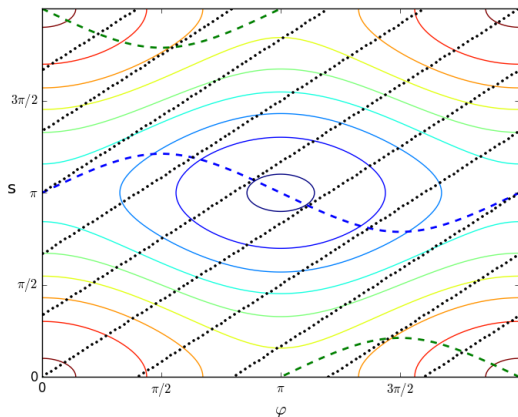


Figure: Level curves of \mathcal{L} for $\mu = a_1/a_2 = 0.5$, $l = 1.2$.

Understanding the behavior of the crests



Understanding the behavior of the Reduced Poincaré function



Understanding the Scattering map

Definition: Highways

Highways are the level curves of \mathcal{L}^* such that

$$\mathcal{L}^*(I, \theta) = \frac{2\pi a_1}{\sinh(\pi/2)}.$$

- The highways are “vertical” in the variables (φ, s)
- We always have a pair of highways. One goes up, the other goes down (this depends on the sign of $\mu = a_1/a_2$)
- The highways give rise to fast diffusing pseudo-orbits

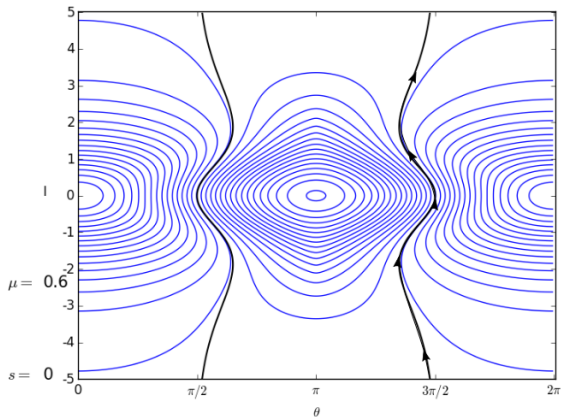
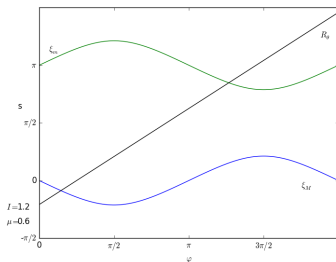


Figure: The scattering map jumps $\mathcal{O}(\varepsilon)$ distances along the level curves of $\mathcal{L}^*(I, \theta)$

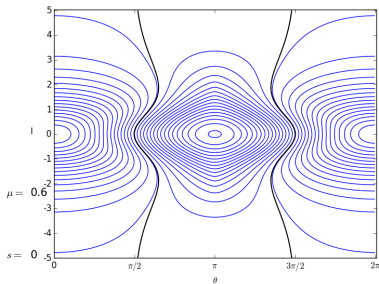
- For $|\mu\alpha(I)| < 1$, there are two crests $\mathcal{C}_{M,m}(I)$ parameterized by:

$$\begin{aligned} s = \xi_M(I, \varphi) &= -\arcsin(\mu\alpha(I) \sin \varphi) \quad \text{mod } 2\pi \\ \xi_m(I, \varphi) &= \arcsin(\mu\alpha(I) \sin \varphi) + \pi \quad \text{mod } 2\pi \end{aligned} \quad (8)$$

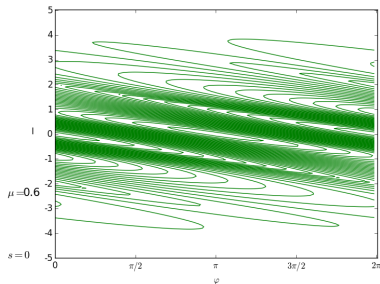


They are “horizontal” crests

- For each I , the line $R(I, \varphi, s)$ and the crest $\mathcal{C}_{M,m}(I)$ have only one intersection point.
- The scattering map S_M associated to the intersections between $\mathcal{C}_M(I)$ and $R(I, \varphi, s)$ is well defined for any $\varphi \in \mathbb{T}$. Analogously for S_m , changing M to m . In the variables $(I, \theta = \varphi - Is)$, both scattering maps S_M, S_m are globally well defined.

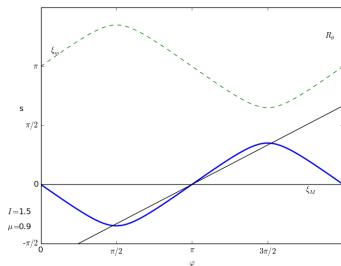


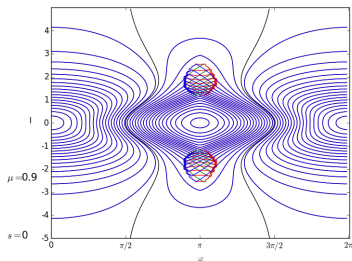
(a) Level curves of $\mathcal{L}_M^*(I, \theta)$



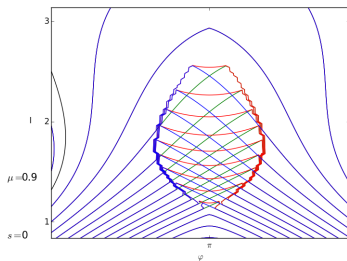
(b) Level curves of $\mathcal{L}_m^*(I, \theta)$

- There are **tangencies** between $\mathcal{C}_{M,m}(I, \varphi)$ and $R(I, \varphi, s)$. For some value of (I, φ, s) , there are **3** points in $R(I, \varphi, s) \cap \mathcal{C}_{M,m}(I)$.
- This implies that there are **3** scattering maps associated to each crest with different domains. (**Multiple Scattering maps**)





(c) The three types of level curves.

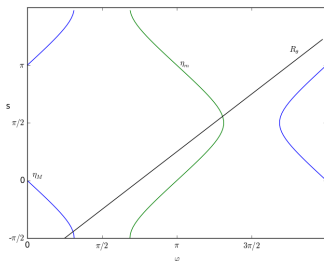


(d) Zoom where the scattering maps are different

Figure: Level curves of $\mathcal{L}_M^*(I, \theta)$, $\mathcal{L}_M^{*(1)}(I, \theta)$ and $\mathcal{L}_M^{*(2)}(I, \theta)$

- For some values of I , $|\mu\alpha(I)| > 1$, the two crests $\mathcal{C}_{M,m}$ are parameterized by:

$$\begin{aligned}\varphi = \eta_M(I, s) &= -\arcsin(\mu\alpha(I) \sin s) \quad \text{mod } 2\pi \\ \eta_m(I, s) &= \arcsin(\mu\alpha(I) \sin s) + \pi \quad \text{mod } 2\pi\end{aligned}\quad (9)$$



They are “vertical” crests

For the values of I and when horizontal crests become vertical, it is not always possible to prolong in a continuous way the scattering maps, so the domain of the scattering map has to be restricted.

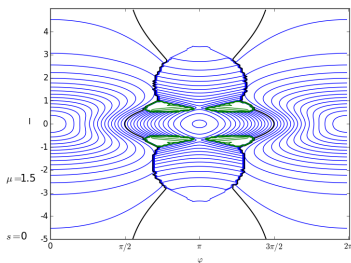


Figure: The level curves of $\mathcal{L}_M^*(I, \theta)$, $\mu = 1.5$.

In green, the region where the scattering map S_M is not defined.

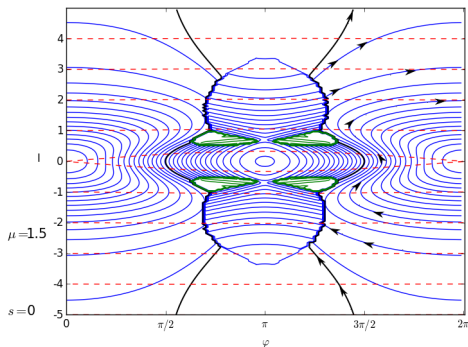


Figure: In red: Inner map, blue: Scattering map, black: Highways

An estimate of the total time of diffusion between $-l^*$ and l^* , along the highway, is

$$T_d = \frac{T_s}{\varepsilon} \left[2 \log \left(\frac{C}{\varepsilon} \right) + \mathcal{O}(\varepsilon^b) \right], \text{ for } \varepsilon \rightarrow 0, \text{ where } 0 < b < 1,$$

with

$$T_s = T_s(l^*, a_1, a_2) = \int_0^{l^*} \frac{-\sinh(\pi l/2)}{\pi a_{10} l \sin \psi_h(l)} dl,$$

where $\psi_h = \theta - l\tau^*(l, \theta)$ is the parameterization of the highway $\mathcal{L}^*(l, \psi_h) = A_2$, and

$$C = C(l^*, a_1, a_2) = 16 |a_1| \left(1 + \frac{1.465}{\sqrt{1 - \mu^2 A^2}} \right)$$

where $A = \max_{l \in [0, l^*]} \alpha(l)$, with $\alpha(l) = \frac{\sinh(\frac{\pi}{2}) l^2}{\sinh(\frac{\pi l}{2})}$ and $\mu = a_1/a_2$.

Note: This estimate quantifies the general optimal diffusion estimate $\mathcal{O}\left(\frac{1}{\varepsilon} \log \frac{1}{\varepsilon}\right)$ of [Berti-Biasco-Bolle 2003], [Cresson-Guillet 2003] and [Treschev 2004].

Thank you very much.

Tack så mycket.

Muchas gracias.

Muito obrigado.

- Deslshams and Schaefer. Arnold Diffusion for a Complete Family of Perturbations. *Regular and Chaotics Dynamics*.2017.